#### Adaptive Load Balancing for Parallel GNN Training Qidong Su, Minjie Wang, Da Zheng, Zheng Zhang

### Abstract

The recent emergence of demand for running Graph Neural Networks (GNNs) on giant real world graphs requires more scalable system designs. Due to the sparse and irregular connections a graph has, parallel GNN training encounters the problem of load imbalance among workers. In this paper, we show that previous techniques based on graph partitioning is insufficient to address the load imbalance caused by GNN sampling algorithms. We thus propose a two-stage strategy to balance the workload adaptively during training. Our evaluation shows that the strategy effectively produces more balanced workloads which accelerates the training by 25%.

# Background

As real world graphs can be gigantic, i.e., consisting of billions of nodes or edges, it is critical to support training GNNs at scale. To parallelize the training procedure, current GNN systems adopt a synchronous data parallelism approach: each worker performs sampling and training in parallel and synchronizes model parameters before the next iteration.



Parallel GNN Training

### Challenges

However, due to the sparse and irregular connections a graph has, the sample sizes among workers can vary drastically, causing severe workload imbalance. Existing systems such as DistDGL leverage off-theshelf graph partitioning algorithms to address the problem.

The approach based on graph partitioning algorithms are not sufficient to balance the GNN workload among trainers. Many graph partitioning algorithms aim at minimizing the number of cross-partition edges or the number of replicated nodes while balancing the number of nodes and edges in each partition. However, the workload balance of parallel GNN training is characterized by a different set of metrics including the number of nodes/edges and the remote nodes ratio of each sampled subgraph and thus demands different solutions.



Imbalanced number of nodes in each layer among trainers



#### Imbalanced number of edges in each layer among trainers



Imbalanced remote nodes ratio in each layer among trainers

### **Proposed Method**

#### **Two-stage load balancing strategy**

Stage 1: Before training, we employ the graph partitioning algorithm in DistDGL to generate static graph partition scheme that minimizes the cut edge set and meanwhile roughly balances the number of nodes and edges among partitions.

**Stage2:** During training, we keep track of the training time of all trainers and adjust their workload accordingly. The basic Idea is to increase the workload of trainers that finish one iteration faster while do the opposite for those that are slower.



After adjusting the batch size of each trainer, we then need to decide the assignments of training node set. Because training nodes that belong to partitions on other machines require network requests to perform neighbor sampling, it is important to balance them among trainers.



## **Evaluation**

#### Setup

**Dataset:** Open Graph Benchmark (ogbn-products, ogbn-papers100M) Hardware: 4 \* AWS EC2 p3dn.24xlarge instances with 8 V100 GPUs on each instance Model: GraphSAGE Hyper-parameters:

Dataset	OGBN-Products		OGBN-Papers100M	
	Light	Heavy	Light	Heavy
Fan-out	15,10,5	10,10,5,5	15,10,5	10,10,5,5
Batch size	2000	2000	2000	5000

adaptive batch size

#### Results





Average iteration time of each trainer. It is well balanced with the adaptive load balancing strategy.